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(54) **METHOD AND APPARATUS FOR
IMPACTING METAL PARTS FOR
AEROSPACE APPLICATIONS**

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See application file for complete search history.

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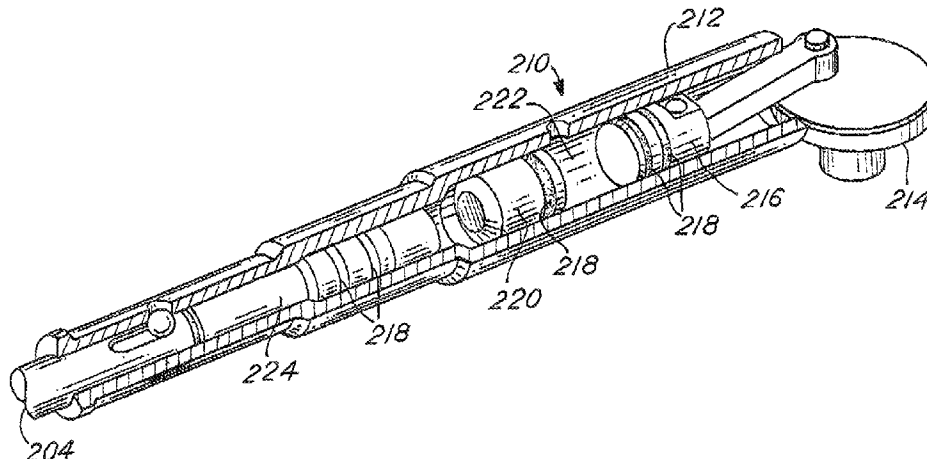
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(57) **ABSTRACT**

An apparatus and method are provided for changing physical characteristics of a workpiece which may have been pre-loaded before being further processed. The workpiece is supported in a fixed position during processing. A driven member applies multiple impacts to one surface of the workpiece. The driven member is operated within adjustable parameters. A controller, having the adjustable parameters, is operatively connected to the driven member for causing the driven member to apply multiple impacts against a surface of the workpiece while under the control of the pre-adjustable parameters for changing physical characteristics of the workpiece.

27 Claims, 4 Drawing Sheets



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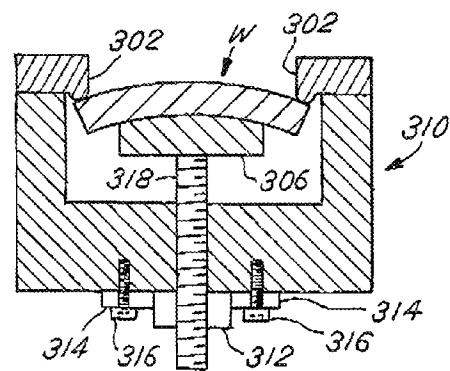
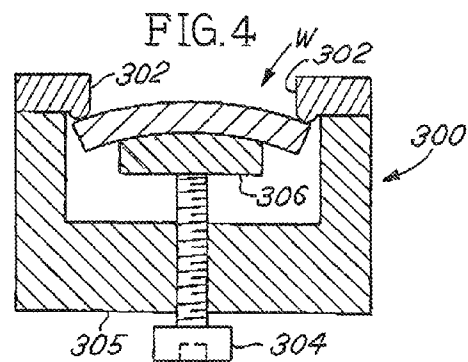
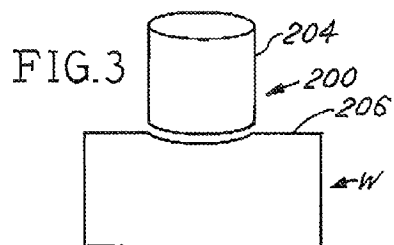
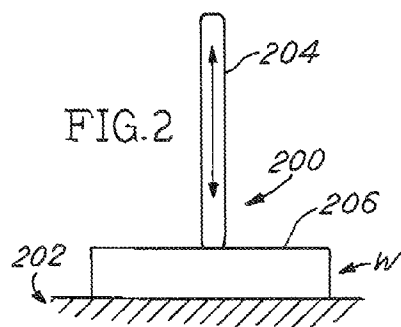
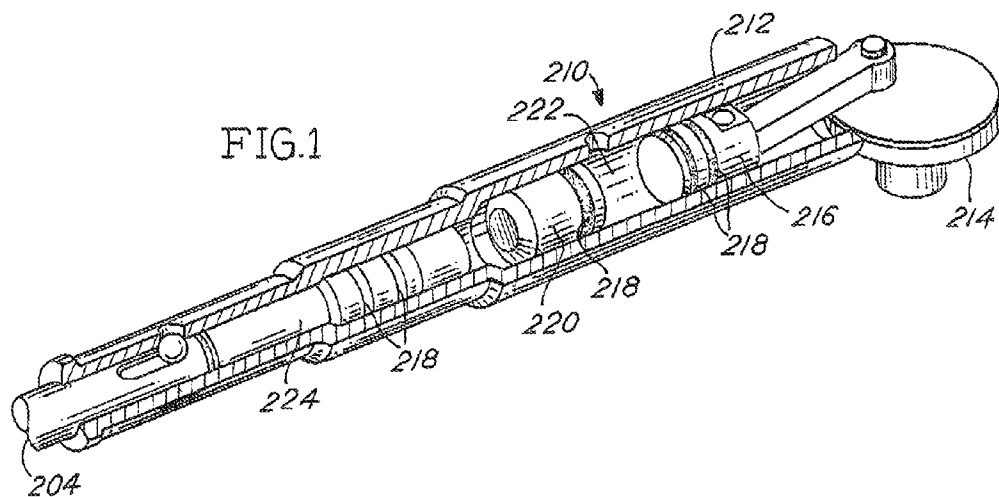
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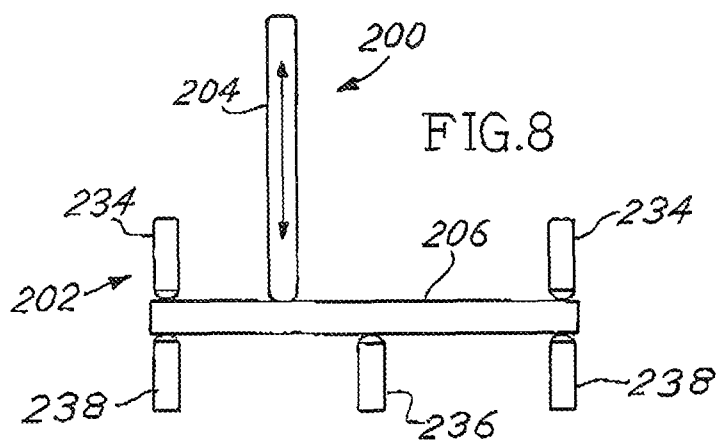
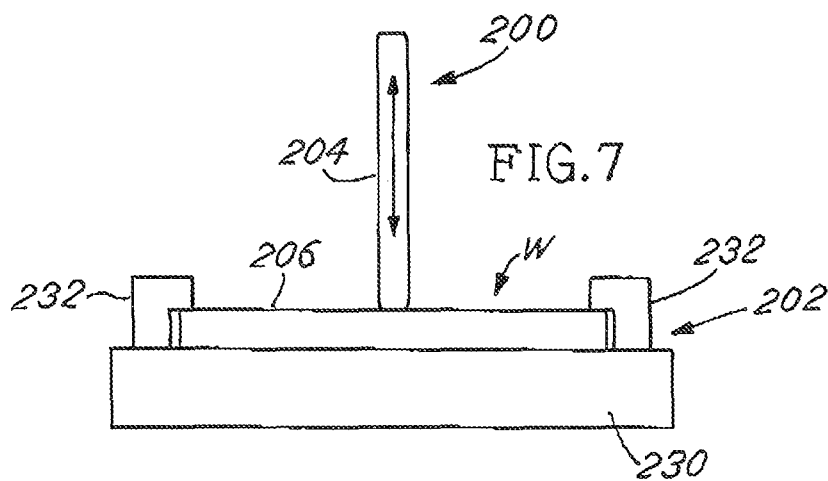
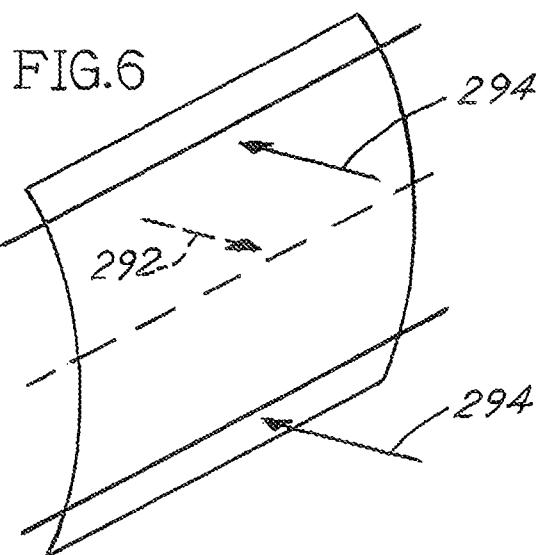
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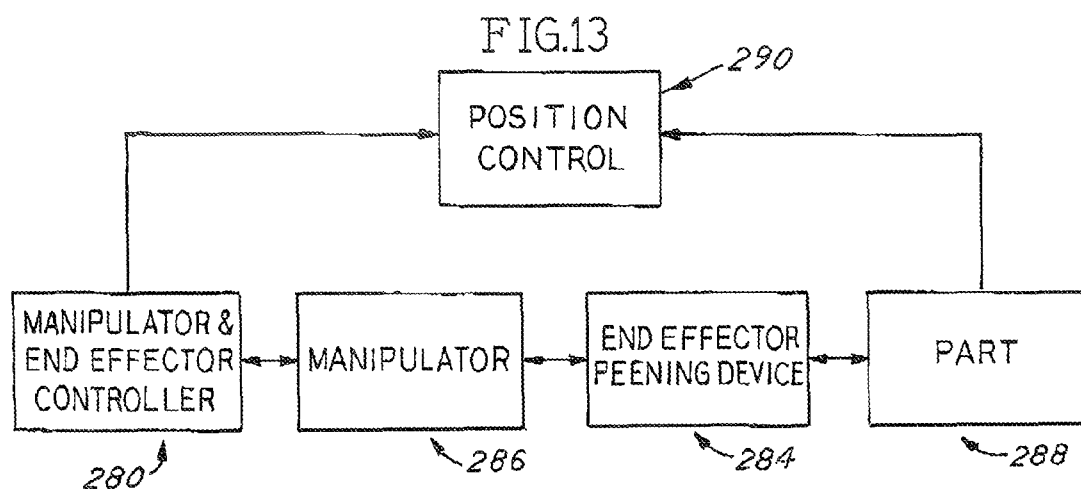
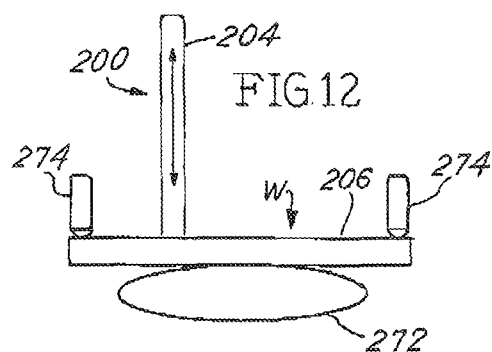
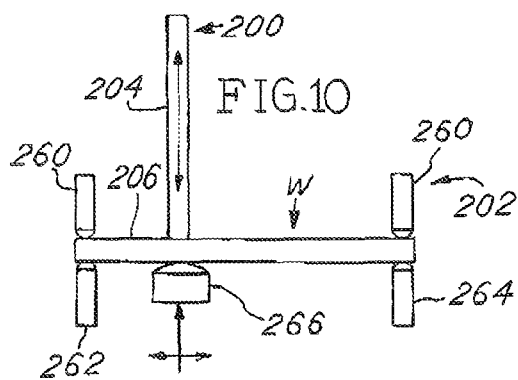
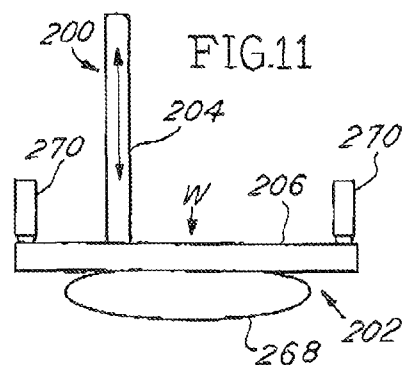
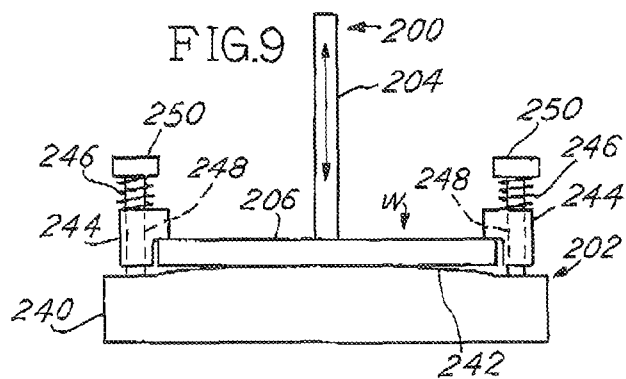
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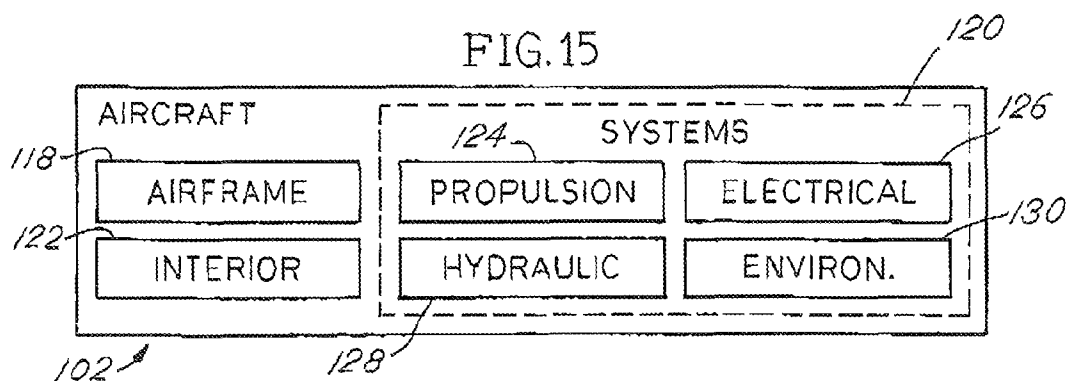
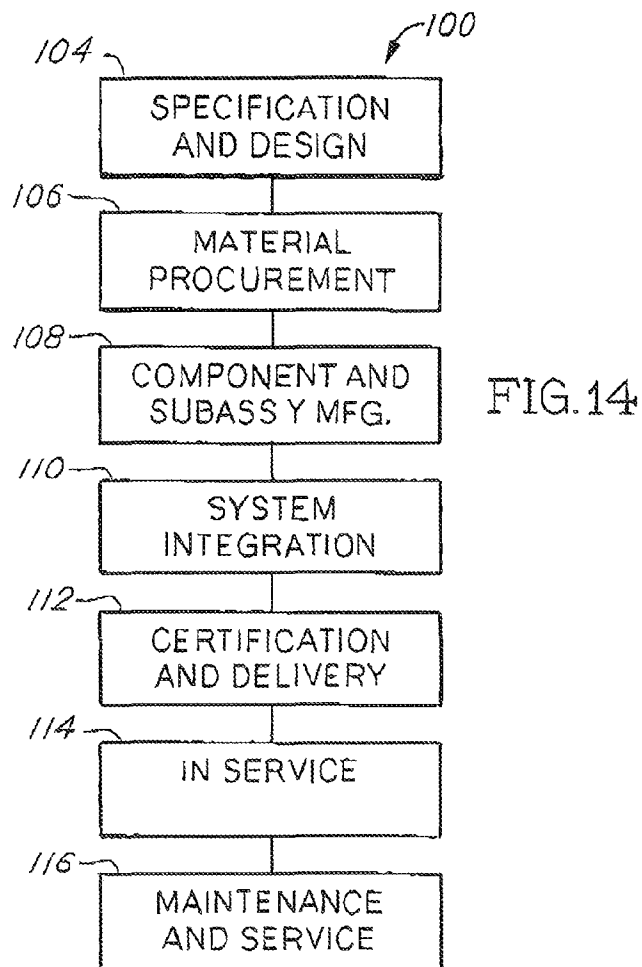
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METHOD AND APPARATUS FOR IMPACTING METAL PARTS FOR AEROSPACE APPLICATIONS

CROSS-REFERENCE TO RELATED APPLICATIONS/INCORPORATION BY REFERENCE

This application is a related application to a United States patent application, entitled "Control Feedback Loop for Real-Time Variable Needle Peen Forming," filed on even date herewith, namely Sep. 19, 2013, under U.S. patent application Ser. No. 14/031,771, which application is also incorporated by reference into this application entitled "METHOD AND APPARATUS FOR IMPACTING METAL PARTS FOR AEROSPACE APPLICATIONS".

FIELD

The disclosure relates to the use of mechanical systems to change physical characteristics of metal parts. More specifically, the disclosure relates to a method and apparatus for mechanically processing, such as by impact peening metal workpieces into final metal components for aircraft and aerospace applications.

BACKGROUND

Currently, metal parts are fabricated from sheet and plate product forms into, but not limited to, fuselage skins, wing skins, and structural areas for aircraft by using systems including shot peening, ultrasonic peening, and laser peening. Shot peening works well on thinner material but is difficult to control, as when precision processing of a part is required. For thicker materials, large shot is required to process the part. Large shot may damage the surface of the part to the point where additional processing steps may be required to meet surface finish requirements. Ultrasonic peening and laser peening are used on both thick and thin metal components, but such systems require a substantial amount of time to process the metal components into the desired final condition. Laser peening requires high investment levels for both initial capital and later recurring costs. A need exists for providing an easily adjustable mechanical system to process components varying from thin sheet metal to those greater than one inch thick, wherein precise finishing of such metal components may be achieved more economically than presently available.

Further limitations and disadvantages of conventional and traditional approaches will become apparent to one of skill in the art, through comparison of such systems with the present disclosure as set forth in the remainder of the present application with reference to the drawings.

BRIEF SUMMARY

In one aspect of the disclosure, an apparatus is provided for changing physical characteristics of a metal workpiece. A support is provided for securing the workpiece in position during processing. A driven member applies multiple impacts to a surface of the workpiece. The driven member is operated within adjustable parameters. A controller, having the adjustable parameters, is operatively connected to the driven member for causing the driven member to apply multiple impacts against the surface of the workpiece while under the control of and/or within a range of the adjustable parameters for changing physical characteristics of the metal workpiece.

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In another aspect of the disclosure, a method is provided for changing the characteristics of a metal workpiece having a surface. The workpiece is supported in position during processing. Multiple impacts are applied to the surface of the workpiece. A controller is provided having adjustable parameters. The impacts are applied within a range of the adjustable parameters for changing physical characteristics of the workpiece.

In still another aspect of the present disclosure, a method is provided for changing the desired physical characteristics or effects of a metal workpiece having a surface until a final metal component is achieved. The method involves pre-loading the workpiece for providing a preliminary contour for the workpiece. Thereafter, the workpiece is securely supported while multiple impacts are applied to the surface of the workpiece W. The multiple impact applying occurs within the range and control of adjustable parameters. The multiple impact applying is continued until the desired physical characteristics or effects are achieved for the final metal component.

The features, functions, and advantages that have been discussed can be achieved independently in various embodiments or may be combined in yet other examples, further details of which can be seen with reference to the following description and drawings.

BRIEF DESCRIPTION OF SEVERAL VIEWS OF THE DRAWINGS

FIG. 1 is a broken-away, perspective view of the interior of one type of rotary impact device used for processing a workpiece with a driven member for achieving a final component;

FIG. 2 is a schematic view of a driven member applying impacts against a workpiece;

FIG. 3 is a schematic view of a driven member transmitting impact energy to a workpiece;

FIG. 4 is a schematic view illustrating one type of fixture for pre-loading a workpiece;

FIG. 5 is a schematic view, similar to FIG. 4, illustrating another type of fixture for pre-loading a workpiece;

FIG. 6 is a schematic view showing a force being applied on the concave side of a workpiece while being pre-loaded in the fixtures of FIG. 4 or 5;

FIG. 7 is a schematic view of one example of a workpiece being held in place by clamps on the surface of a support while impacts are being applied to the workpiece by a driven member;

FIG. 8 is a view similar to FIG. 7 of another example of a workpiece being held in place by clamps while impacts are being applied to the workpiece by a driven member;

FIG. 9 is a view similar to FIGS. 7 and 8 of still another example of a workpiece resting on a raised anvil surface of a support while being held in place by biasing clamps;

FIG. 10 is yet another example, similar to FIGS. 7-9, of a workpiece being held in place by clamps with a movable anvil opposing a driven member applying impacts to the workpiece;

FIG. 11 is yet a further example, similar to FIGS. 7-10, showing an air bladder anvil supporting the lower surface of the workpiece while a drive member applies impacts to the upper surface of the workpiece and while clamps hold the workpiece in place on the anvil;

FIG. 12 is a view, similar to FIGS. 7-11, showing another type of air bladder anvil supporting the lower surface of a workpiece and opposing the driven member against a surface of the workpiece while being held in place by clamps,

FIG. 13 is a flow diagram representing an apparatus and method for impacting a workpiece;

FIG. 14 is a flow diagram of aircraft production and service methodology; and

FIG. 15 is a block diagram of an aircraft.

DETAILED DESCRIPTION

Referring to the drawings, examples of the disclosure may be described in the context of an aircraft manufacturing and service method **100** as shown in FIG. 14 and an aircraft **102** as shown in FIG. 15. During pre-production, exemplary method **100** may include specification and design **104** of the aircraft **102** and material procurement **106**. During production, component and subassembly manufacturing **108** and system integration **110** of the aircraft **102** takes place. Thereafter, the aircraft **102** may go through certification and delivery **112** in order to be placed in service **114**. While in service by a customer, the aircraft **102** is scheduled for routine maintenance and service **116** (which may also include modification, reconfiguration, refurbishment, and so on).

Each of the processes of method **100** may be performed or carried out by a system integrator, a third party, and/or an operator (e.g., a customer). For the purposes of this description, a system integrator may include without limitation any number of aircraft manufacturers and major-system subcontractors; a third party may include without limitation any number of vendors, subcontractors, and suppliers; and an operator may be an airline, leasing company, military entity, service organization, and so on.

As shown in FIG. 15, the aircraft **102** produced by exemplary method **100** may include an airframe **118** with a plurality of systems **120** and an interior **122**. Examples of high-level systems **120** include one or more of a propulsion system **124**, an electrical system **126**, a hydraulic system **128**, and an environmental system **130**. Any number of other systems may be included. Although an aerospace example is shown, the principles of the disclosure may be applied to other industries, such as the automotive industry.

Apparatus and methods embodied herein may be employed during any one or more of the stages of the production and service method **100**. For example, components or subassemblies corresponding to production process **108** may be fabricated or manufactured in a manner similar to components or subassemblies produced while the aircraft **102** is in service. Also, one or more apparatus example, method example, or a combination thereof may be utilized during the production stages **108** and **110**, for example, by substantially expediting assembly of or reducing the cost of an aircraft **102**. Similarly, one or more of apparatus example, method example, or a combination thereof may be utilized while the aircraft **102** is in service, for example and without limitation, to maintenance and service **116**.

Referring to FIGS. 14 and 15, the description of the present disclosure to be hereinafter provided generally falls within category 108 "Component and Subass'y Mfg." and also generally falls within category 118 "Airframe."

The present disclosure is directed to an apparatus and method for changing physical characteristics of metal workpieces or parts by multiple impacts. The workpiece may be sheet metal or plate or an extrusion or an assembly and may have a thickness range of 0.062 to 2.00 inches. Each workpiece W may have different dimensions in length, width, and thickness. Each workpiece W may have multiple surfaces which receive multiple impacts. The metal itself may be any metal such as aluminum, titanium or metal alloys. In essence,

the metal or metal alloy workpiece may exist in a variety of geometries and configurations.

Referring to FIGS. 2 and 3, an apparatus **200** is provided for changing physical characteristics of a metal workpiece.

The workpiece W is securely positioned upon a support **202**. Although the support **202** is shown in the accompanying drawings as being in a horizontal position, it is to be understood that the support **202** for the workpiece W may be in a substantially vertical position and virtually at any angle between the vertical and horizontal positions of the workpiece W. A driven member **204** is provided for applying multiple impacts to the surface **206** of the workpiece W. The driven member **204** desirably has a hardness greater than that of the workpiece W. The multiple impacts from the driven member **204** change physical characteristics or effects of the workpiece W until a final useful component, such as for use on an aircraft, is achieved.

As disclosed, the workpiece W may have a variety of geometries, including length. Each support **202** has certain dimensions and is able to receive and process each workpiece W. For example, in some cases, a workpiece W may be impacted in its entirety on a given support **202** by the driven member **204**. In other cases, a lengthy workpiece W may be processed in consecutive sections of the same workpiece. The leading section of such a lengthy workpiece W may be processed while being secured on the support. The leading section is moved forward while adjacent trailing sections of similar dimensions are impacted in a stepwise manner.

In all of the workpieces W being processed, each workpiece W is supported in a fixed position during impacting by the driven member **204** over the entire surface **206** which is the equivalent of the impact coverage area. As to be described hereinafter in detail, the driven member **204** is controlled by a manipulator and an end effector for impacting the entire coverage area of an entire workpiece W or of each section of a lengthy workpiece W while being secured in position on a support **202**.

Referring to FIG. 3, the driven member **204** applies multiple impacts to the surface **206** of a workpiece W and creates impact energy that moves as a stress wave from the driven member **204** to the surface of the workpiece W. The stress wave is then transferred from the surface **206** as an internal compressive layer within the workpiece W. The relationship of the compressive layer to the tensile layer of the workpiece W acts to change the workpiece into a component having changed physical characteristics or effects such as a desired contour for a desired final component.

The following description of the apparatus **200** provides details of one type of device **210** for driving the driven member **204** and of multiple possible types of supports **202** for the workpiece W. These descriptions will be followed by a description of the method of operation of the apparatus **200** by reference to the flow diagram shown in FIG. 13.

Referring to FIG. 1, one example of a device, generally **210**, for applying multiple impacts by the driven member **204** on a workpiece W is shown. The illustrated example device **210** is electrically driven. Such a device **210** may also be driven hydraulically or pneumatically. It is to be understood that other types of devices may be utilized provided that any such other device is capable of generating and imparting an impact energy into and through the driven member **204**. The illustrated device **210** is a crank mechanism and includes a housing **212**. The housing **212** has a rotatable crank **214** that is connected to a shaft (not shown) connected to an electric drive motor (not shown). The crank **214** provides multiple beats per minute by the driven member **204** on the surface **206** of the workpiece W and initially provides a driving force for

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a piston **216**. The piston **216** is reciprocally mounted within the housing **212** and has an O-ring **218** bearing against the cylindrical interior wall of the housing **212**.

Spaced from the piston **216** is a ram **220**, which is reciprocally mounted within the housing and has an O-ring **218** thereon. The ram **220** cooperates with the piston **216** to form an air spring **222** therebetween. The air spring **222** drives the ram **220** which accelerates a beat-piece **224**. The air spring **222** drives the ram **220** against a beat-piece **224** when it is moving forward and retrieves the ram **220** when the piston **216** retracts. The beat-piece **224** includes a pair of O-rings **218** for sealing against the housing **212**. The beat-piece **224** transfers energy of the ram **220** to an end of the driven member **204** which applies multiple impacts against the workpiece W. The impacts provide energy for moving a stress wave through the driven member **204** to the surface **206** of the workpiece W.

As described above, the device **210** is used to cause multiple impacts by the driven member **204** to be applied against the surface **206** of the workpiece W. Following is a discussion of multiple examples of supports **202** for the workpiece W during the impacting by the driven member **204** against the surface **206** of each workpiece W being processed regardless of the length of the workpiece W. In all cases, the driven member **204** applies impacts across the entire coverage area of the workpiece W, which is secured in position by a support **202** during the entire time that impacts are being applied.

The following description discloses various types of anvils located on the opposite side of the impacts by the driven member **204** against the surface **206** of the workpiece W. Each support **202** to be described functions as an anvil that forcibly opposes the impact side of the workpiece W away from the driven member **204**. When a workpiece W is resting on a flat surface of a support **202** and is processed on the flat surface, portions of the workpiece W begin to rise off the flat surface of the support **202** and a gap forms between the flat surface and the risen portions of the workpiece W. This creates an undesired loss of energy due to the workpiece W vibrating in free air.

In essence, the supports **202** for the workpiece W, to be described in the following examples, reduce such loss of energy. Each example support **202** secures the workpiece W during processing. Each example support **202** further provides acts as an anvil on the opposite side of the workpiece W while the driven member **204** is applying multiple impacts to the surface **206** of the workpiece W. Further, clamps of various types cooperate with the supports **202** to secure the workpiece W in place during impacting by the driven member **204**. The clamps, to be described, are elongated and may extend for the entire length of the support **202** during impacting by the driven member **204**. The clamps are positioned to secure each workpiece at a selected location. In each example support that follows, the driven member **204** is being driven by a device, such as the device **210**, described above.

Referring to FIG. 7, the workpiece W is mounted on a flat plate **230** which is the support **202** for the workpiece W. The impact energy from the driven member **204** moves as a stress wave to the surface **206** of the workpiece. Clamps **232**, which are elongated, secure the workpiece W against the flat plate **230** to thereby avoid the compressive forces from the impacting to raise portions of the workpiece W and create a loss of energy.

Referring to FIG. 8, the support **202** comprises a pair of opposed clamps **234**, that are elongated and secure the workpiece W to avoid the raising of the workpiece W during impacting. At least one central clamp **236**, which is elongated, is mounted on the opposite side of the workpiece W and acts

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as an anvil in opposition to the impacts from the driven member **204** against the surface **206** of the workpiece W. A stress wave moves through the driven member **204** to the surface **206** of the workpiece W. The resulting energy is then transferred into space on the opposite side of the surface of the workpiece W. A pair of optional clamps **238** may be placed on a side of the surface **206** opposite to the clamps **234**. The clamps **234** and the clamps **236** and **238** secure the workpiece W while reducing the loss of energy by the workpiece W during the impacting of the workpiece W by the driven member **204**.

FIG. 9 is another alternative example of supporting a workpiece W wherein a plate **240** is provided with a raised anvil portion **242** which acts in opposition to the driven member **204** impacting the upper surface **206** of the workpiece W. In this example, a pair of biased clamps **244**, which are elongated, are provided to secure the workpiece W. Springs **246** bias the clamps **244** to secure the workpiece W against the raised anvil portion **242**. The springs **246** are positioned around a fixed post **248** having an upper plate **250**. The springs **246** are mounted between the plate **250** and the clamps **244**. A stress wave moves through the workpiece W and into the plate **240** while the workpiece W is being secured. The raised portion **242** acts as an opposing anvil to the impacting by the driven member **204** on the surface **206** of the workpiece W.

FIG. 10 is still another example of a support **202** for the workpiece W. Clamps **260**, which are elongated, are mounted against the surface **206** of the workpiece W. On the opposite side of the workpiece W, a clamp **262** is provided in opposition to one clamp **260** acting against the opposite surface of the workpiece W. An optional clamp **264**, which may also be elongated, is positioned against the opposite side of the workpiece W in opposition to the clamp **260**. A movable anvil **266** is mounted in opposition to the driven member **204** at the opposite side of the workpiece W. The anvil **266** is movable in X, Y and Z directions and acts in opposition to the impacting by the driven member **204** against the surface **206**. The workpiece W is secured and there is a reduced loss of energy of a stress wave that passes to the upper surface **206** of the workpiece W during impacting by the driven member **204**.

With reference to FIG. 11, there is still a further example of a support **202** for a workpiece W during processing as the driven member **204** is impacting the surface **206** of the workpiece W. An air bladder anvil **268** is provided on the opposite side of the surface **206** of the workpiece W from the driven member **204** as impacts are applied to the upper surface **206**. The air bladder anvil **268**, which may be elongated, has an adjustable shape during impacting. A pair of clamps **270**, which are elongated, bear against the upper surface **206** of the workpiece W. A reduced loss of energy results by holding the workpiece W while the air bladder anvil **268** absorbs the stress wave.

Referring to FIG. 12, the structure of the support **204** is similar to that of FIG. 11 in that clamps **274**, which are elongated, bear against the surface **206** of the workpiece W. The air bladder anvil **272** of this example is a preformed shaped air bladder anvil, as opposed to the adjustable shape of the air bladder anvil **268** of FIG. 11 and functions in a similar manner as the example of FIG. 11. The clamps **274** secure the surface S of the workpiece W to reduce energy loss which is accomplished by all the above examples (FIGS. 7-11). Anvils are provided for each support **202** for reducing the amount of energy lost.

As stated previously, referring to FIG. 13, a flow diagram is shown wherein a controller **280** is provided for operating a manipulator and an end effector and is represented in the flow

diagram box **280** as “Manipulator & End Effector Controller.” The device **210** and the driven member **204** are mounted on the end effector **284** for applying multiple impacts at a given frequency against the surface **206** of the workpiece W. The driven member **204** is represented in the flow diagram box **284** as “End Effector Peening Device.” A manipulator is provided for locating the end effector and the driven member **204** while the driven member **204** moves across the workpiece W and while impacting the surface **206** of the workpiece W. The workpiece W is identified in the flow diagram box **288** as “Part.” A control is identified in the flow diagram box **290** as “Position Control.” The method of operation for changing physical characteristics of the workpiece W or “Part” will be described with reference to the flow diagram FIG. **13**. Each operating part shown in the flow diagram will be briefly described along with each of their functions while referring also to previously described operating components.

The Position Control **290** locates the position of the workpiece W (Part-Box **290**) positioned on a support **202**. Once the workpiece W (Part) is securely mounted on the support **202**, the position location of the workpiece W is communicated to the Manipulator and End Effector Controller (Box **280**). The Manipulator and End Effector Controller **280** receives the workpiece W (Part) position and the path data from the System Control (not shown in the flow diagram of FIG. **13**). The Manipulator and End Effector Controller drive a motion control system through a programmed path of travel. The Manipulator and End Effector Controller communicate with the end effector peening device or driven member **204** at the current location of the end effector relative to the workpiece W. The Manipulator locates and controls the end effector to move in a preplanned motion path. The End Effector Peening Device (Box **284**) causes the driven member **204** to apply multiple impacts to the workpiece W (Part) as commanded by the Controller (Box **280**). The driven member **204** moves across the entire surface **206** of the workpiece W while secured on a support **202** under the control of the end effector and the manipulator which are controlled by the parameters.

In carrying out the method of using the described apparatus for applying impacts to a workpiece W, the workpiece W is securely positioned on a support **202** which may be any one of the above supports **202**. The Position Control provides the Manipulator and the End Effector Controller with the position of the workpiece W on the support **204**.

The Manipulator and End Effector Controller are provided with the adjustable parameters for changing physical characteristics of the workpiece W into a desired final product. The adjustable parameters for changing physical characteristics of the workpiece include an energy level for the impacts, which may be in the range of 1-35 Joules, on the workpiece W, a rate of application of the impacts on the workpiece W and the coverage area of the impacts on the workpiece W. The impacts are applied by the driven member **204** to the surface of the workpiece W as the end effector and manipulator move the driven member **204** across the entire coverage area or surface **206** of the workpiece W. This occurs when the entire workpiece W or a section thereof has been mounted in a secure position on a support **202**, as described above. The device **210** is mounted on the end effector. The driven member **204** of the device **210** is under the control of the Manipulator and End Effector Controller (Box **280**) which further includes the parameters. The impacting is continued until a desired final product has been achieved.

The basic components of both the apparatus and method of the present disclosure have been described above. In selected situations, an added method step and apparatus may be provided for initially pre-loading the workpiece W for forming

the workpiece W into a preliminary contour. A description of the pre-loading of the workpiece W for forming a preliminary contour on a workpiece W is described below.

The following disclosure relates generally to impact peening following a pre-loading step. Here the pre-loading provides a more efficient process such as a shortened overall processing time when the pre-loading is performed prior to impacting the workpiece W by the driven member **204**. The forming of the workpiece W can be accomplished with less power and more coverage area by the impacting of the workpiece W with the driven member **204** when the workpiece W has been first pre-loaded.

Referring to FIG. **6**, it is schematically shown that by forcibly pressing on the central concave side of a workpiece W, as illustrated by an arrow **292**, a desired contour is achieved and may be nearly equivalent to the ultimate contour for the workpiece W. As shown, opposing grippers **302** are applied against the workpiece W as illustrated by arrows **294**. As the impacts are applied to the surface **206** of the prestressed workpiece W by the driven member **204**, as represented by the arrow **292**, the pre-loading begins to relax the workpiece W and the contour from the pre-loading is maintained or increased by subsequent multiple impacts.

FIG. **4** shows a fixture, generally **300**, that has elongated grippers **302** fixed at the upper outer portion of the fixture **300** and a threaded bolt **304** is located in the lower, central portion **305** of the fixture **300**. A workpiece W is formed in the fixture **300** by a forming member **306**, having a contoured upper surface **307** on the underside of the workpiece W. The upper/outer zones of the upper surface of the workpiece W are being held by the grippers **302** as the bolt **304** forces the forming member **306** upwardly against the lower surface of the workpiece W to pre-load the workpiece W.

Referring to FIG. **5** an alternate fixture **310** is shown. Like the fixture **300**, the construction of the fixture **310** is substantially the same as fixture **300** except FIG. **5** shows the use of a hydraulic piston assembly **312** that drives the forming member **306** against the lower surface of the workpiece W being pre-loaded in the fixture **310**. The hydraulic piston assembly **310** is fixed to the underside of the fixture **310** by an outer flange **314** having threaded bolts **316** secured to the underside of the fixture **310**. A piston rod **318** is secured to the underside of the contoured forming member **306**. Again the upper/outer zones of the upper surface of the workpiece are being held by the grippers **302** as the piston rod **318** forces the forming member **306** upwardly against the lower surface of the workpiece to pre-load the workpiece W.

The workpiece W is first pre-loaded for forming a preliminary contour on the workpiece W, such as shown in FIGS. **4**, **5** and **6**. The workpiece W or a section of a workpiece is transferred from a pre-loading fixture **300** or **310** to a support **202** for further processing by applying multiple impacts from the driven member **204** against the convex side of the workpiece W. The processing of the pre-loaded workpiece W is then continued in the manner described above relative to multiple impacts applied by the driven member **204** with the impacts being applied to the convex side of the workpiece W, as seen in FIG. **6**.

While the disclosure has been described with reference to certain embodiments, it will be understood by those skilled in the art that various changes may be made and equivalents may be substituted without departing from the spirit and scope of the present disclosure. In addition, many modifications may be made to adapt a particular situation or material to the teachings of the present disclosure without departing from its scope. Therefore, it is intended that the present disclosure not be limited to the particular examples disclosed, but that the

present disclosure will include all examples falling within the scope of the appended claims.

What is claimed is:

1. Apparatus for changing physical characteristics of a metal workpiece having a surface, the apparatus comprising:
 - a support for the workpiece;
 - a driven member for applying multiple impacts to a surface of the workpiece; and
 - a controller having adjustable parameters operatively connected to the driven member to operate the driven member for applying multiple impacts against the surface of the workpiece within a range of the adjustable parameters for changing physical characteristics of the metal workpiece;
 wherein the support further includes elongated clamps for holding the workpiece on the support for the workpiece.
2. The apparatus of claim 1 wherein the support for the workpiece has a surface and wherein the workpiece has a second surface which bears against the surface of the support.
3. The apparatus of claim 2 wherein the support for the workpiece includes clamps bearing against the surface of the workpiece and the support further includes at least one additional clamp bearing against the second surface of the workpiece.
4. The apparatus of claim 3 wherein the support includes further clamps, the further clamps bear against the second surface of the workpiece and directly oppose the clamps bearing against the surface of the workpiece.
5. The apparatus of claim 1 wherein the support for the workpiece includes a raised surface, the raised surface providing an anvil for opposing the impacts of the driven member against the workpiece.
6. The apparatus of claim 5 wherein the support further includes biased clamps for securing the workpiece on the support and for securing the workpiece against the raised surface of the support.
7. The apparatus of claim 2 wherein the support for the workpiece includes an anvil bearing against the second surface of the workpiece in opposition to the driven member applying impacts to the surface of the workpiece, the anvil being moveable in X, Y, and Z directions for opposing the impacts against the workpiece from the driven member.
8. The apparatus of claim 2 wherein the apparatus includes at least one pair of clamps for bearing against the surface and the second surface of the workpiece during the applying of the multiple impacts to the surface of the workpiece from the driven member.
9. The apparatus of claim 2 wherein the support includes an air bladder anvil bearing against the second surface of the workpiece, and the apparatus further includes a pair of spaced clamps bearing against the surface of the workpiece.
10. The apparatus of claim 9 wherein the air bladder anvil is a preformed and shaped air bladder anvil.
11. The apparatus of claim 1 wherein the apparatus includes a crank mechanism for driving the driven member, the crank mechanism having a continuous reciprocally moving ram, the ram creating energy transformed into impact energy by the driven member, the impact energy moving as a stress wave from the driven member into the surface of the workpiece.
12. The apparatus of claim 1 wherein the adjustable parameters include energy levels of the impacts from the driven member on the workpiece, a rate of application of the impacts by the driven member on the workpiece, and a coverage area of the impacts on the workpiece by the driven member for changing physical characteristics of the metal workpiece.

13. The apparatus of claim 12 wherein the energy levels of the impacts are in the range of 1-35 Joules.

14. The apparatus of claim 1 including a controller, a manipulator and an end effector wherein the controller operates the manipulator and the end effector to have the driven member apply the multiple impacts against the surface of the workpiece within the range of the adjustable parameters.

15. The apparatus of claim 1 including a fixture for pre-loading the workpiece before the driven member applies impacts to the workpiece.

16. A method for changing physical characteristics of a metal workpiece having a surface, the method comprising the steps of:

supporting the workpiece;

providing a controller;

providing the controller with adjustable parameters for changing physical characteristics of the workpiece;

applying multiple impacts to the surface of the workpiece;

controlling the applying step with the controller having the adjustable parameters for changing physical characteristics of the workpiece; and

holding the workpiece on the support using elongated clamps.

17. The method of claim 16 wherein the method further includes securing the workpiece during the supporting step.

18. The method of claim 16 including the further steps of providing a second surface on the workpiece and clamping the surface of the workpiece and of clamping the second surface of the workpiece for directly opposing the clamping of the surface of the workpiece.

19. The method of claim 16 including the step of providing a second surface on the workpiece and providing an anvil bearing against the second surface of the workpiece for opposing the multiple impacts to the surface of the workpiece.

20. The method of claim 16 wherein the method further includes the step of providing biasing clamps for securing the workpiece while supporting the workpiece during the changing of physical characteristics of the workpiece.

21. The method of claim 16 including the step of providing a second surface on the workpiece and providing an anvil for bearing against the second surface of the workpiece in opposition to the multiple impacts to the surface of the workpiece, the anvil being moveable in x, y and z directions for directly opposing the impacts against the workpiece.

22. The method of claim 16 wherein the workpiece has a second surface and the method includes the step of providing an air bladder anvil bearing against the second surface of the workpiece, the method further including the step of clamping the workpiece against the surface of the workpiece.

23. The method of claim 16 wherein the adjustable parameters for changing physical characteristics of the workpiece are energy levels for the impacts on the workpiece, a rate of application of the impacts on the workpiece, and a coverage area of the impacts on the workpiece.

24. The method of claim 23 wherein energy levels are in the range of 1-35 Joules.

25. The method of claim 16 wherein the workpiece has multiple surfaces.

26. A method for changing physical characteristics of a metal workpiece having multiple surfaces until a final metal component is achieved, the method comprising the steps of:

- pre-loading the workpiece for forming a preliminary contour on the workpiece;
- supporting the workpiece having the preliminary contour;
- providing a controller;

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providing the controller with adjustable parameters for changing physical characteristics of the workpiece having the preliminary contour;

applying multiple impacts to a surface of the workpiece; and

controlling the applying step with the adjustable parameters for changing physical characteristics of the workpiece until the final metal component is achieved.

27. The method of claim **26** including the step of selecting a surface of the workpiece for the pre-loading step as being a concave side of the workpiece, and providing a fixture for the workpiece during pre-loading.

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